

SEMESTER V

S. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	EE3501	Power System Analysis	PCC	3	0	0	3	3
2.	EE3591	Power Electronics	PCC	3	0	0	3	3
3.	EE3503	Control Systems	PCC	3	0	0	3	3
4.		Professional Elective I	PEC	3	0	0	3	3
5.		Professional Elective II	PEC	3	0	0	3	3
6.		Professional Elective III	PEC	3	0	0	3	3
7.		Mandatory Course-I ^{&}	MC	3	0	0	3	0
PRACTICALS								
8.	EE3511	Power Electronics Laboratory	PCC	0	0	3	3	1.5
9.	EE3512	Control and Instrumentation Laboratory	PCC	0	0	4	4	2
TOTAL				21	0	7	28	21.5

[&] Mandatory Course-I is a Non-credit Course (Student shall select one course from the list given under MC-I)

SEMESTER VI

S. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
THEORY								
1.	EE3601	Protection and Switchgear	PCC	3	0	0	3	3
2.	EE3602	Power System Operation and Control	PCC	3	0	0	3	3
3.		Open Elective – I*	OEC	3	0	0	3	3
4.		Professional Elective IV	PEC	3	0	0	3	3
5.		Professional Elective V	PEC	3	0	0	3	3
6.		Professional Elective VI	PEC	3	0	0	3	3
7.		Mandatory Course-II ^{&}	MC	3	0	0	3	0
8.		NCC Credit Course Level 3 [#]		3	0	0	3	3 [#]
PRACTICALS								
9.	EE3611	Power System Laboratory	PCC	0	0	3	3	1.5
TOTAL				21	0	3	24	19.5

* Open Elective – I shall be chosen from the emerging technologies

[&] Mandatory Course-II is a Non-credit Course (Student Shall select one course from the list given under MC-II)

[#] NCC Credit Course level 3 is offered for NCC students only. The grades earned by the students will be recorded in the Mark Sheet, however the same shall not be considered for the computation of CGPA

MANDATORY COURSES I

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	MX3081	Introduction to Women and Gender Studies	MC	3	0	0	3	0
2.	MX3082	Elements of Literature	MC	3	0	0	3	0
3.	MX3083	Film Appreciation	MC	3	0	0	3	0
4.	MX3084	Disaster Risk Reduction and Management	MC	3	0	0	3	0

MANDATORY COURSES II

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	MX3085	Well Being with Traditional Practices - Yoga, Ayurveda and Siddha	MC	3	0	0	3	0
2.	MX3086	History of Science and Technology in India	MC	3	0	0	3	0
3.	MX3087	Political and Economic Thought for a Humane Society	MC	3	0	0	3	0
4.	MX3088	State, Nation Building and Politics in India	MC	3	0	0	3	0
5.	MX3089	Industrial Safety	MC	3	0	0	3	0

ELECTIVE - MANAGEMENT COURSES

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	GE3751	Principles of Management	HSMC	3	0	0	3	3
2.	GE3752	Total Quality Management	HSMC	3	0	0	3	3
3.	GE3753	Engineering Economics and Financial Accounting	HSMC	3	0	0	3	3
4.	GE3754	Human Resource Management	HSMC	3	0	0	3	3
5.	GE3755	Knowledge Management	HSMC	3	0	0	3	3
6.	GE3792	Industrial Management	HSMC	3	0	0	3	3

PROFESSIONAL ELECTIVE COURSES : VERTICALS

VERTICAL I : POWER ENGINEERING

SL. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	EE3001	Utilization and Conservation of Electrical Energy	PEC	3	0	0	3	3
2.	EE3002	Under Ground Cable Engineering	PEC	3	0	0	3	3
3.	EE3003	Substation Engineering and Automation	PEC	3	0	0	3	3
4.	EE3004	HVDC and FACTS	PEC	3	0	0	3	3
5.	EE3005	Energy Management and Auditing	PEC	3	0	0	3	3
6.	EE3006	Power Quality	PEC	3	0	0	3	3
7.	EE3007	Smart Grid	PEC	3	0	0	3	3
8.	EE3008	Restructured Power Market	PEC	3	0	0	3	3

VERTICAL II : CONVERTERS AND DRIVES

SL. NO.	COURSE CODE	COURSE TITLE	CATEGORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	EE3009	Special Electrical Machines	PEC	2	0	2	4	3
2.	EE3010	Analysis of Electrical Machines	PEC	2	0	2	4	3
3.	EE3011	Multilevel Power Converters	PEC	2	0	2	4	3
4.	EE3012	Electrical Drives	PEC	2	0	2	4	3
5.	EE3013	SMPS and UPS	PEC	2	0	2	4	3
6.	EE3014	Power Electronics for Renewable Energy Systems	PEC	2	0	2	4	3
7.	EE3015	Control of Power Electronics Circuits	PEC	2	0	2	4	3

VERTICAL III : EMBEDDED SYSTEMS

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	EE3016	Embedded System Design	PEC	2	0	2	4	3
2.	EE3017	Embedded C-programming	PEC	2	0	2	4	3
3.	EE3018	Embedded Processors	PEC	2	0	2	4	3
4.	EE3019	Embedded Control for Electric Drives	PEC	2	0	2	4	3
5.	EE3020	Smart System Automation	PEC	2	0	2	4	3
6.	EE3021	Embedded System for Automotive Applications	PEC	2	0	2	4	3
7.	EE3022	VLSI Design	PEC	2	0	2	4	3
8.	EE3023	MEMS and NEMS	PEC	2	0	2	4	3
9.	EE3024	Digital Signal Processing System Design	PEC	2	0	2	4	3

VERTICAL IV : ELECTRIC VEHICLE TECHNOLOGY

SL. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT PERIODS	CREDITS
				L	T	P		
1.	EE3025	Electric Vehicle Architecture	PEC	3	0	0	3	3
2.	EE3026	Design of Motor and Power Converters for Electric Vehicles	PEC	2	0	2	4	3
3.	EE3027	Electric Vehicle Design, Mechanics and Control	PEC	2	0	2	4	3
4.	EE3028	Design of Electric Vehicle Charging System	PEC	2	0	2	4	3
5.	EE3029	Testing of Electric Vehicles	PEC	2	0	2	4	3
6.	EE3030	Grid Integration of Electric Vehicles	PEC	3	0	0	3	3
7.	EE3031	Intelligent Control of Electric Vehicles	PEC	2	0	2	4	3

11. Programming PIC architecture with software tools.

TOTAL :45 PERIODS

COURSE OUTCOMES:

After studying the above subject, students should have the:

CO1: Ability to write assembly language program for microprocessor.

CO2: Ability to write assembly language program for microcontroller

CO3: Ability to design and implement interfacing of peripheral with microprocessor and microcontroller

CO4: Ability to analyze, comprehend, design and simulate microprocessor based systems used for control and monitoring..

CO5: Ability to analyze, comprehend, design and simulate microcontroller based systems used for control and monitoring.

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	2	1	2	3	-	-	-	1.5	-	-	-	3	3	1	3
CO2	2	1	2	3	-	-	-	1.5	-	-	-	3	3	1	3
CO3	2	1	2	3	-	-	-	1.5	-	-	-	3	3	1	3
CO4	2	1	2	3	-	-	-	1.5	-	-	-	3	3	1	3
CO5	2	1	2	3	-	-	-	1.5	-	-	-	3	3	1	3
Avg	2	1	2	3	-	-	-	1.5	-	-	-	3	3	1	3

EE3501

POWER SYSTEM ANALYSIS

L T P C

3 0 0 3

COURSE OBJECTIVES:

- Impact knowledge on need for operational studies, and To model the power system under steady state operating condition.
- To understand and apply iterative techniques for power flow analysis.
- To model of carry out short circuit studies for power system during symmetrical fault.
- To model of carry out short circuit – studies during
- To study about the various methods for analyzing power system stability

UNIT I POWER SYSTEM

9

Need for system planning and operational studies - Power scenario in India - Power system components, Representation - Single line diagram - per unit quantities - p.u. impedance diagram - p.u. reactance diagram, Network graph Theory - Bus incidence matrices, Primitive parameters, Formation of bus admittance matrix – Direct inspection method – Singular

Transformation method.

UNIT II POWER FLOW ANALYSIS 9

Bus classification - Formulation of Power Flow problem in polar coordinates - Power flow solution using Gauss Seidel method - Handling of Voltage controlled buses - Power Flow Solution by Newton Raphson method – Flow charts – Comparison of methods.

UNIT III SYMMETRICAL FAULT ANALYSIS 9

Assumptions in short circuit analysis - Symmetrical short circuit analysis using Thevenin's theorem - Bus Impedance matrix building algorithm (without mutual coupling) - Symmetrical fault analysis through bus impedance matrix - Post fault bus voltages - Fault level - Current limiting reactors.

UNIT IV UNSYMMETRICAL FAULT ANALYSIS 9

Symmetrical components - Sequence impedances - Sequence networks - Analysis of unsymmetrical faults at generator terminals: LG, LL and LLG - unsymmetrical fault occurring at any point in a power system.

UNIT V STABILITY ANALYSIS 9

Classification of power system stability – Rotor angle stability - Power-Angle equation – Steady state stability - Swing equation – Solution of swing equation by step by step method - Swing curve, Equal area criterion - Critical clearing angle and time, Multi-machine stability analysis – modified Euler method.

TOTAL : 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students should have the:

- CO1: Ability to model the power system under steady state operating condition.
- CO2: Ability to carry out power flow analysis using.
- CO3: Ability to infer the significance of short circuit studies in designing circuit breakers.
- CO4: Ability to analyze the state of the power system for various unsymmetrical faults.
- CO5: Ability to analyze the stability of power system using different methods.

TEXT BOOKS:

1. John J. Grainger, William D. Stevenson, Jr, 'Power System Analysis', Mc Graw Hill Education (India) Private Limited, New Delhi, 2017.
2. Kothari D.P. and Nagrath I.J., 'Power System Engineering', Tata McGraw-Hill Education, 3rd edition 2019.
3. Hadi Saadat, 'Power System Analysis', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 21st reprint, 2010.

REFERENCES

1. Pai M A, 'Computer Techniques in Power System Analysis', Tata Mc Graw-Hill Publishing Company Ltd., New Delhi, Second Edition, 2007.
2. J. Duncan Glover, Mulukutla S.Sarma, Thomas J. Overbye, 'Power System Analysis & Design', Cengage Learning, Fifth Edition, 2012.
3. P. Venkatesh, B. V. Manikandan, A. Srinivasan, S. Charles Raja, "Electrical Power Systems: Analysis, Security and Deregulation" Prentice Hall India (PHI), second edition - 2017
4. Gupta B.R., 'Power System - Analysis and Design', S. Chand Publishing, Reissue

edition 2005.

- Kundur P., 'Power System Stability and Control', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 2013

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PS01	PS02	PS03
CO1	3	2	2	1	1	-	-	-	1	-	-	-	1	-	2
CO2	3	3	3	2	1	-	-	-	1	-	-	-	1	1	1
CO3	3	3	3	2	1	-	-	-	1	-	-	1	1	1	1
CO4	3	2	2	2	2	-	-	-	1	-	-	1	1	1	2
CO5	3	3	2	2	2	-	-	-	1	-	-	1	1	1	1
Avg	3	2.6	2.4	1.8	1.4	-	-	-	1	-	-	1	1	1	1.4

EE3591

POWER ELECTRONICS

L T P C
3 0 0 3

COURSE OBJECTIVES:

- To understand the various applications of power electronic devices for conversion, control and conditioning of the electrical power and to get an overview of different types of power semiconductor devices and their dynamic characteristics.
- To understand the operation, characteristics and performance parameters of controlled rectifiers
- To study the operation, switching techniques and basic topologies of DC-DC switching regulators.
- To learn the different modulation techniques of pulse width modulated inverters and to understand harmonic reduction methods.
- To study the operation of AC voltage controller and various configurations of AC voltage controller.

UNIT I SWITCHING POWER SUPPLIES

9

MOSFET dynamic behavior - driver and snubber circuits - low power high switching frequency switching Power supplies, buck, boost, buck-boost converters – Isolated topologies – resonant converters - switching loss calculations and thermal design.

UNIT II INVERTERS

9

IGBT: Static and dynamic behavior - single phase half bridge and full bridge inverters - VSI :(1phase and three phase inverters square wave operation) - Voltage control of inverters single, multi pulse, sinusoidal, space vector modulation techniques– various harmonic elimination techniques-CSI

UNIT III UNCONTROLLED RECTIFIERS

9

Power Diode – half wave rectifier – mid-point secondary transformer based full wave rectifier – bridge rectifier – voltage doubler circuit – distortion factor – capacitor filter for low power rectifiers – LC filters – Concern for power quality – three phase diode bridge.

UNIT IV CONTROLLED RECTIFIERS

9

SCR-Two transistor analogy based turn- ON – turn ON losses – thermal protection – controlled converters (1 pulse, 2 pulse, 3 pulse, 6 pulse) - displacement factor – ripple and harmonic factor - power factor mitigation, performance parameters – effect of source inductance - inverter angle limit.

UNIT V AC PHASE CONTROLLERS

9

TRIAC triggering concept with positive and negative gate pulse triggering, TRIAC based phase controllers - various configurations for SCR based single and three phase controllers.

TOTAL: 45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Understand the operation of semiconductor devices and dynamic characteristics and to design & analyze the low power SMPS

CO2: Analyze the various uncontrolled rectifiers and design suitable filter circuits

CO3: Analyze the operation of the n-pulse converters and evaluate the performance parameters

CO4: Understand various PWM techniques and apply voltage control and harmonic elimination methods to inverter circuits.

CO5: Understand the operation of AC voltage controllers and its applications.

TEXT BOOKS:

1. Ned Mohan, T.M.Undeland, W.P.Robbins, "Power Electronics: Converters, applications and design", John Wiley and Sons, 3rd Edition (reprint), 2009
2. Rashid M.H., Power Electronics Circuits, Devices and Applications, Prentice Hall India, 3rd Edition, New Delhi, 2004.

REFERENCES:

1. Cyril. W.Lander, Power Electronics, McGraw Hill International, Third Edition, 1993.
2. P.S.Bimbhra, Power Electronics, Khanna Publishers, Third Edition 2003
3. Philip T.Krein, Elements of Power Electronics, Oxford University Press, 2013.
4. P.C.Sen, Power Electronics, Tata McGraw-Hill, 30th reprint, 2008.

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	-	-	2	1	-	-	3	3	3	3	3
CO2	3	3	3	3	-	-	1	-	-	-	-	-	3	3	3
CO3	3	3	3	3	-	-	2	1	-	-	2	-	3	3	3
CO4	3	3	3	3	-	-	1	1	-	-	2	3	3	3	3
CO5	3	3	3	3	-	-	1	1	-	-	2	3	3	3	3
Avg.	3	3	3	3	-	-	1.5	1	-	-	2.25	3	3	3	3

EE3503

CONTROL SYSTEMS

**LT P C
3 0 0 3**

COURSE OBJECTIVES:

- To make the students to familiarize with various representations of systems.
- To make the students to analyze the stability of linear systems in the time domain and frequency domain.
- To make the students to analyze the stability of linear systems in the frequency domain.

3. Katsuhiko Ogata, “Modern Control Engineering”, PHI Learning Private Ltd, 5th Edition, 2010
 4. NPTEL Video Lecture Notes on “Control Engineering” by Prof.S.D.Agashe, IIT Bombay.

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3	-	-	1	-	-	-	3	3	3	3
CO2	3	3	3	3	3	-	-	1	-	-	-	3	3	3	3
CO3	3	3	3	3	3	-	-	1	-	-	-	3	3	3	3
CO4	3	3	3	3	3	-	-	1	-	-	-	3	3	3	3
CO5	3	3	3	3	3	-	-	1	-	-	-	3	3	3	3
Avg.	3	3	3	3	3	-	-	1	-	-	-	3	3	3	3

EE3511

POWER ELECTRONICS LABORATORY

**L T P C
0 0 3 1.5**

COURSE OBJECTIVES:

- To study the VI characteristics of SCR, TRIAC, MOSFET and IGBT.
- To analyze the performance of semi converter, full converter, step up, step down choppers by simulation and experimentation.
- To study the behavior of voltage waveforms of PWM inverter applying various modulation techniques.
- To design and analyze the performance of SMPS.
- To study the performance of AC voltage controller by simulation and Experimentation.

LIST OF EXPERIMENTS:

1. Characteristics of SCR and TRIAC.
2. Characteristics of MOSFET and IGBT.
3. AC to DC half controlled converter.
4. AC to DC fully controlled converter.
5. Step down and step up MOSFET based choppers.
6. IGBT based single phase PWM inverter.
7. IGBT based three phase PWM inverter.
8. AC Voltage controller.
9. Switched mode power converter.
10. Simulation of PE circuits (1 Φ & 3 Φ semi converter, 1 Φ & 3 Φ full converter, dc-dc converters, ac voltage controllers).

TOTAL :45 PERIODS

COURSE OUTCOMES:

Upon the successful completion of the course, students will be able to:

CO1: Determine the characteristics of SCR, IGBT, TRIAC, MOSFET and IGBT

CO2: Find the transfer characteristics of full converter, semi converter, step up and step down choppers by simulation experimentation.

CO3: Analyze the voltage waveforms for PWM inverter using various modulation techniques.

CO4: Design and experimentally verify the performance of basic DC/DC converter topologies used for SMPS.

CO5: Understand the performance of AC voltage controllers by simulation and experimentation

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3	-	-	1.5	-	-	-	3	3	3	3
CO2	3	3	3	3	3	-	-	1.5	-	-	-	3	3	3	3
CO3	3	3	3	3	3	-	-	1.5	-	-	-	3	3	3	3
CO4	3	3	3	3	3	-	-	1.5	-	-	-	3	3	3	3
CO5	3	3	3	3	3	-	-	1.5	-	-	-	3	3	3	3
Avg	3	3	3	3	3	-	-	1.5	-	-	-	3	3	3	3

EE3512

CONTROL AND INSTRUMENTATION LABORATORY

LT P C
0 0 4 2

COURSE OBJECTIVES:

- To make the students familiarize with various representations of systems.
- To make the students analyze the stability of linear systems in the time domain and frequency domain.
- To make the students design compensator based on the time and frequency domain Specifications.
- To develop linear models mainly state variable model and transfer function model
- To make the students to design a complete closed loop control system for the physical systems.

LIST OF EXPERIMENTS:

1. Analog (op amp based) simulation of linear differential equations.
2. Numerical Simulation of given nonlinear differential equations.
3. Real time simulation of differential equations.
4. Mathematical modeling and simulation of physical systems in at least two fields.
 - Mechanical
 - Electrical
 - Chemical process
5. System Identification through process reaction curve.
6. Stability analysis using Pole zero maps and Routh Hurwitz Criterion in simulation platform.
7. Root Locus based analysis in simulation platform.
8. Determination of transfer function of a physical system using frequency response and Bode's asymptotes.
9. Design of Lag, lead compensators and evaluation of closed loop performance.
10. Design of PID controllers and evaluation of closed loop performance.
11. Discretization of continuous system and effect of sampling.
12. Test of controllability and observability in continuous and discrete domain in simulation platform.
13. State feedback and state observer design and evaluation of closed loop performance.

14. Mini Project 1: Simulation of complete closed loop control systems including sensor and actuator dynamics.
 15. Mini Project 2: Demonstration of a closed loop system in hardware.

TOTAL :60 PERIODS

COURSE OUTCOMES:

At the end of this course, the students will demonstrate the ability

- CO1: To model and analyze simple physical systems and simulate the performance in analog and digital platform.
 CO2: To design and implement simple controllers in standard forms.
 CO3: To design compensators based on time and frequency domain specifications.
 CO4: To design a complete closed control loop and evaluate its performance for simple physical systems.
 CO5: To analyze the stability of a physical system in both continuous and discrete domains.

MAPPING OF COs WITH POs AND PSOs

COs	POs												PSOs		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3	-	-	1.5	-	-	-	2	3	3	3
CO2	3	3	3	3	3	-	-	1.5	-	-	-	2	3	3	3
CO3	3	3	3	3	3	-	-	1.5	-	-	-	2	3	3	3
CO4	3	3	3	3	3	-	-	1.5	-	-	-	2	3	3	3
CO5	3	3	3	3	3	-	-	1.5	-	-	-	2	3	3	3
Avg	3	3	3	3	3	-	-	1.5	-	-	-	2	3	3	3

EE3601

PROTECTION AND SWITCHGEAR

L T P C
3 0 0 3

COURSE OBJECTIVES:

- To understand the significance of protection, protection schemes and role of earthing.
- To study the characteristics, functions and application areas of various relays.
- To acquire practical knowledge about common faults in power system apparatus and applying suitable protective schemes.
- To understand the functioning of static relays and Numerical protection concepts.
- To understand the problems associated with circuit breaking and to discuss about various circuit breakers.

UNIT I

PROTECTION SCHEMES

9