

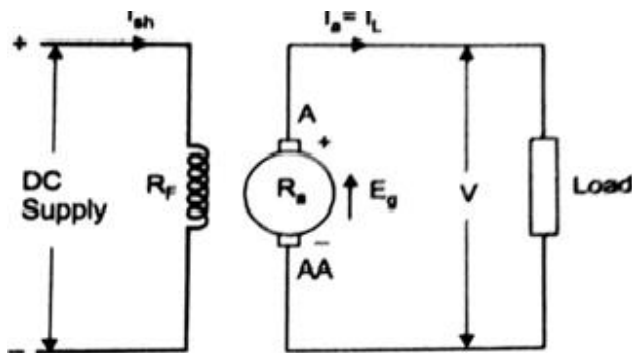
3.7 TYPES OF DC MOTOR:

1. Separately excited DC motor

2. Self-excited dc motor

- Series motor
- Shunt motor
- Compound motor
 1. Long shunt compound motor
 2. Short shunt compound motor

SEPARATELY EXCITED DC MOTOR:

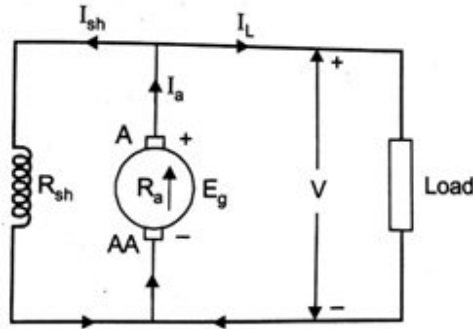


- Field winding and armature are separated.
- Field winding is excited by a separate DC source-separately excited dc motor.
- $I_a = I_L$
- $E_b = V - I_a R_a - V_{brush}$

DC SERIES MOTOR:

- Field winding is connected in series with armature.
- Less number of turns.
- R_{se} –resistance of series field winding-small.
- I_L =line current
- I_a =series field
- $V = E_b + I_a R_a + I_{sc} R_{sc} + V_{brush}$.
- $V = E_b + (R_a + R_{se}) I_a$.
- $\Phi \propto I_{se} \propto I_a$

DC SHUNT MOTOR:

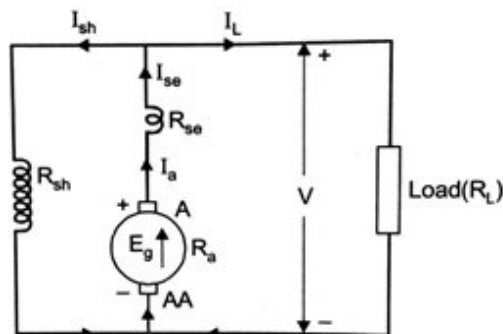


- Field winding is connected across the armature.
- More number of turns with less cross-sectional area.
- Rsh is the shunt field winding
- Ra is the armature resistance.
- Ra is small, Rsh is large.
- Voltage v = voltage across the armature and field winding.
- I_L is the line current, divided into two paths
 1. Field winding
 2. Armature winding
- $I_L = I_a + I_{sh}$
- I_a = armature current
- I_{sh} = shunt field current
- $I_{sh} = V / R_{sh}$
- $V = E_b + I_a R_a + V_{brush}$
- $\Phi \propto I_{sh}$
- Input is constant, so flux is constant.
- Also known as constant flux motor.

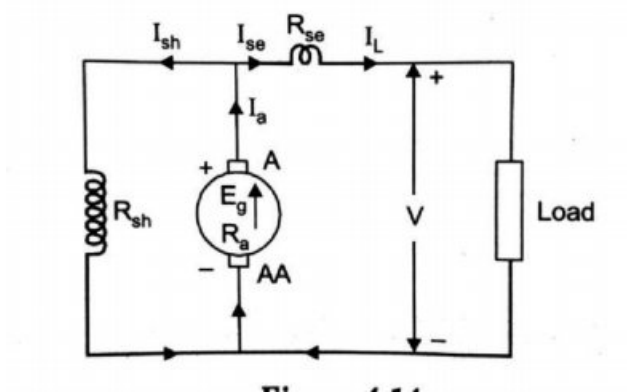
DC COMPOUND MOTOR:

1. LONG SHUNT:

- Shunt field winding is connected to both the armature and the field winding.
- $I_L = I_{sc} + I_{sh}$
- $I_{se} = I_a$
- $I_L = I_a + I_{sh}$
- $I_{sh} = V / R_{sh}$
- Voltage equation $V = E_b + I_a(R_a + R_{se}) + V_{brush}$



2. SHORT SHUNT:



- Shunt field winding is connected across armature and series field winding is connected in series.
- $I_L = I_{se}$
- $I_L = I_a + I_{sh}$
- $I_L = I_{se} = I_a + I_{sh}$
- Voltage drop = $v - I_L R_{se}$
- $V = E_b + I_a R_a + V_{brush}$
- $I_{sh} = \frac{V - I_L R_{se}}{R_{sh}}$.