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Question Paper Code: 40425

B.E./B.Tech. DEGREE EXAMINATIONS, NOVEMBER/DECEMBER 2021.

Fifth Semester

Electronics and Communication engineering

EC 8074 — ROBOTICS AND AUTOMATION

(Regulations 2017)

(Common to Medical Electronics)

Time: Three hours Maximum: 100 marks

Answer ALL questions.

PART A — $(10 \times 2 = 20 \text{ marks})$

- 1. List any four advantages of using robot in material handling applications
- 2. Define robot anatomy.
- 3. Why the servomotors are most preferred actuator for robot manipulators?
- 4. What are the advantages of hydraulic drive over pneumatic drives?
- 5. Differentiate between forward and inverse kinematics.
- 6. List out any two drawbacks in vacuum gripper.
- 7. Why is SLAM a hard problem?
- 8. What is fuzzy logic?
- 9. What is mean by virtual reality?
- 10. List any two robots that are using artificial intelligence.

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PART B — $(5 \times 13 = 65 \text{ marks})$

11. (a) How are the robotic manipulators classified? Give the comparison of robots on the basis of coordinate systems.

Or

- (b) Write a short note on the following features of a robot
 - (i) Spatial resolution
 - (ii) Accuracy
 - (iii) Repeatability
 - (iv) Degrees of freedom.
- 12. (a) With a neat circuit diagram, explain how the speed and direction of a DC motor can be controlled.

Or

- (b) Discuss in detail about the use of sensors in industrial robotics and automated manufacturing systems.
- 13. (a) Using DH method and by symbolic sketch, write down the transformation matrices for each link and determine the position and orientation of end effector with respect to the base in a cartesian robot configuration.

Or

- (b) Write the factors to be considered for the selection of gripper for specific application and also explain anyone gripper with a neat sketch.
- 14. (a) Discuss about robot programming languages and also explain teachpendant for robotic system.

Or

- (b) Discuss in detail about cartesian control for robot manipulators.
- 15. (a) AI and machine learning can improve robotics Justify.

Or

(b) Write the different types of unmanned vehicles and explain any one in detail.

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PART C — $(1 \times 15 = 15 \text{ marks})$

16. (a) Discuss in detail about tele-operated robotic surgery and cognitive robotics.

Or

(b) Explain the selection procedure of a robot for arc welding application. Also explain the necessary precautions that must be addressed while using this robot in a shop-floor along with other automated machines.

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